



# A Hybrid Metaheuristic For Yard Crane Scheduling Problem considering Energy Consumption

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# Problem introduction

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**Yard crane scheduling problem (YCSP)** determines the allocation and schedule of the yard cranes (RTG's and RS's) to the pending operational jobs.



Rubber Tyred Gantry crane (RTG)



Reach Stacker (RS)

(Source: <https://www.termavi.com/en/multimedia-2/>)

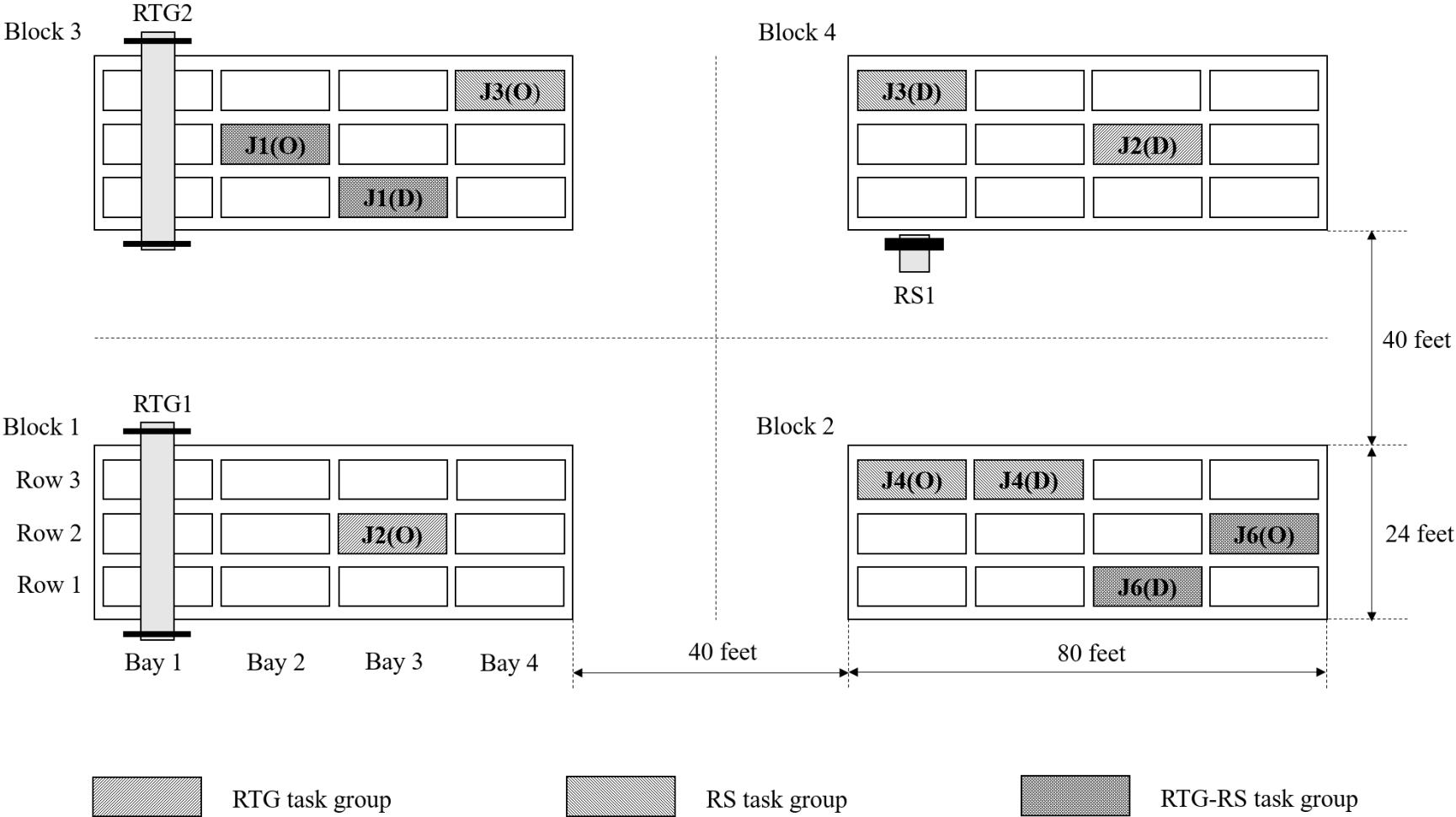
# Problem introduction

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## Three task groups:

- RTG only tasks
- RS only tasks
- RTG-RS tasks

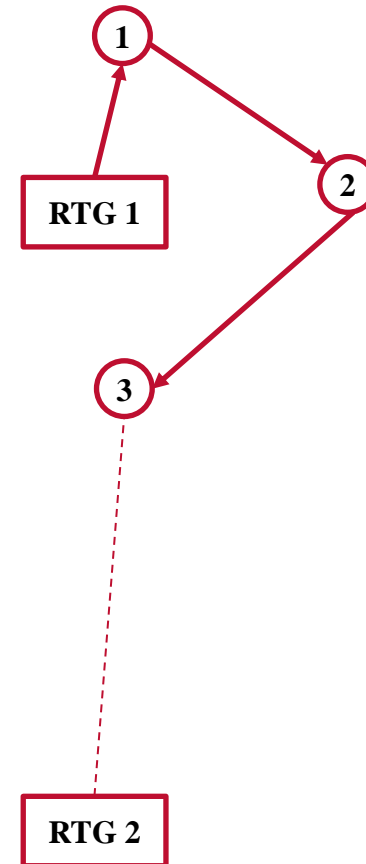
# Problem introduction



# YCSP Objectives

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- Minimise the tardiness of container operations
- Minimise the energy consumption of yard cranes



He, J., Huang, Y., & Yan, W. (2015). Yard crane scheduling in a container terminal for the trade-off between efficiency and energy consumption. *Advanced Engineering*

Sha, M., Zhang, T., Lan, Y., Zhou, X., Qin, T., Yu, D., & Chen, K. (2017). Scheduling optimization of yard cranes with minimal energy consumption at container terminals. *Computers & Industrial Engineering*, 113, 704-713.

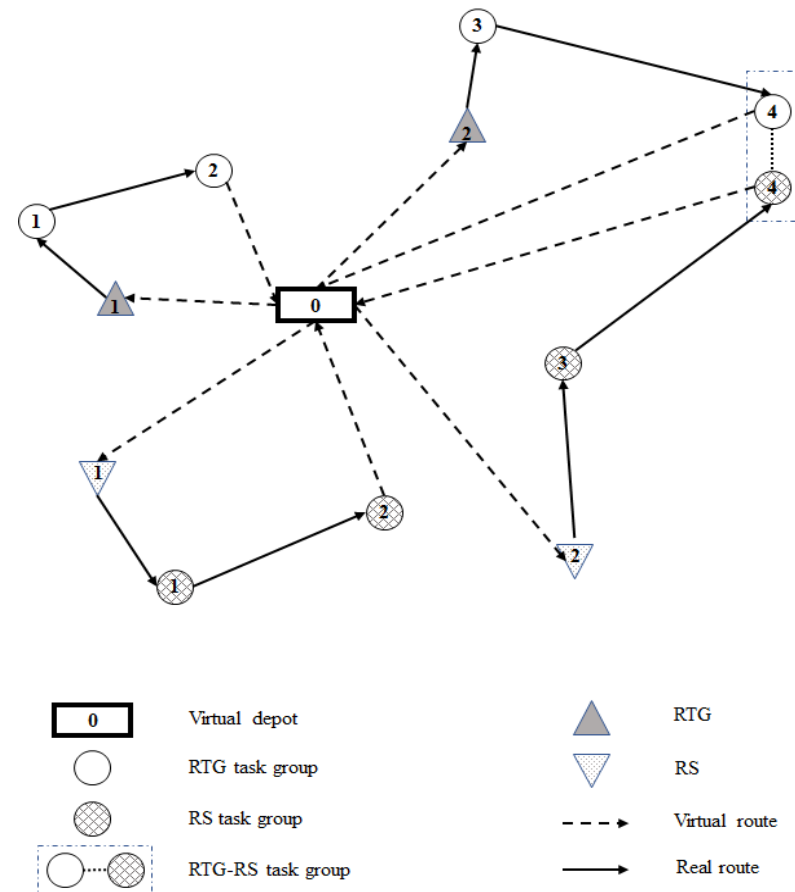
Peng, Y., Wang, W., Song, X., & Zhang, Q. (2016). Optimal allocation of resources for yard crane network management to minimize carbon dioxide emissions. *Journal of cleaner production*, 131, 649-658.

# Model formulation

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**YCSP** is formulated as a **vehicle routing problem with time windows**.

- Each crane RTG/RS is considered as a vehicle
- Each container movement task is considered as a job/customer
- Each job has a independent time window



# Model formulation

## Decision variables

- $U_{kij}$  1 if arc  $(i,j)$  is traversed by RTG or RS  $k$ , and 0 otherwise
- $V_i$  Service starting time of RTG or RS for customer  $i$

## Mixed integer nonlinear model for bi-objective

- Tardiness of all jobs *Minimise*  $Z_1 = \sum_{i \in J} \max(V_i + s_i - b_i, 0)$ ,
- Energy consumption: moving energy and working energy of RTGs, moving energy and working energy of RSs

*Minimise*  $Z_2$

$$\begin{aligned}
 &= \sum_{k \in R_{RTG}} \sum_{i \in W} \sum_{j \in W, j \neq i} (t_{ij}^{RTG} \gamma^{RTG} + d_{ij} \delta^{RTG}) U_{kij} + \sum_{i \in J_{RTG}} (s_i \gamma^{RTG} + h_i \beta^{RTG}) \\
 &+ \sum_{k \in R_{RS}} \sum_{i \in W} \sum_{j \in W, j \neq i} d_{ij} \delta^{RS} U_{kij} + \sum_{i \in J_{RS}} h_i \beta^{RS}
 \end{aligned}$$



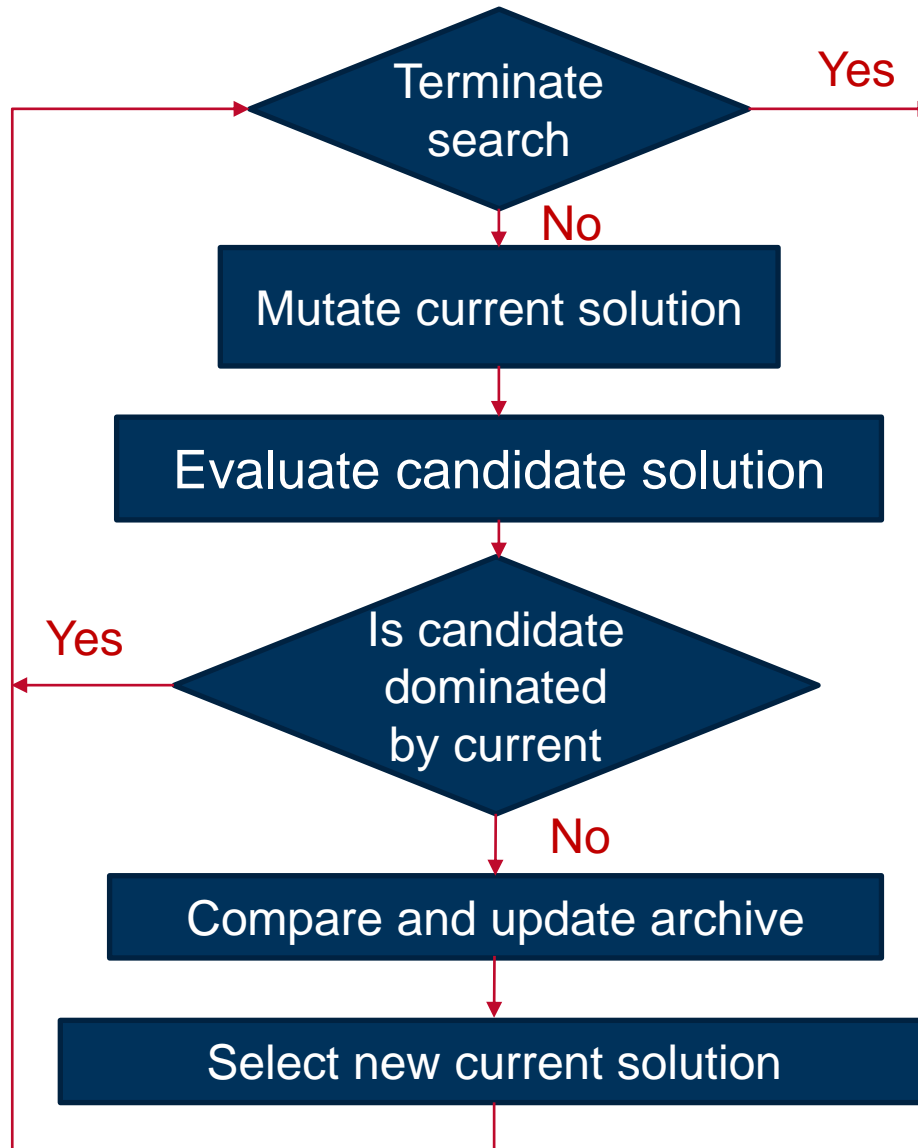
# A hybrid metaheuristic for YCSP

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- A Pareto Archived Evolution Strategy (PAES)
- Simulated Annealing as local search
- Completing a job includes set-up time and processing time. The set-up time is sequence dependent. (Akpinar et al., 2012; Ruiz et al., 2004; Abreu et al., 2020)

# A hybrid metaheuristic for YCSP

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# A hybrid metaheuristic for YCSP

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- Chromosome example

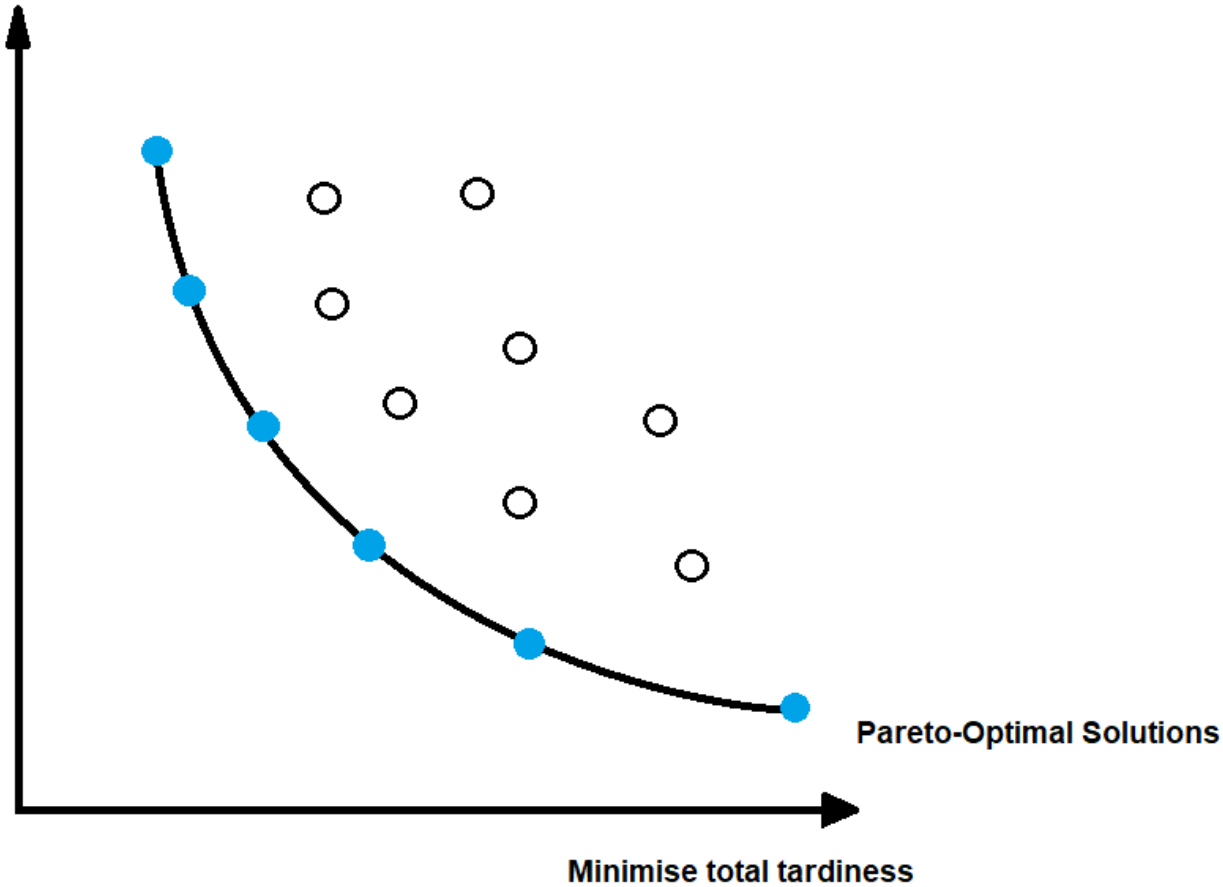
Crane 1	2	1	5	7	10	4
Crane 2	9	3	6			
Crane 3	8	11	12			

- Mutations
  - Insert a random job to another position
  - Swap a number of jobs between two cranes
  - Reverse a number of jobs in a random crane

# Pareto frontier example



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Minimise energy consumption



# Case study

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PortForward



**THE YARD CRANE SCHEDULING MODULE (YCSM)**

1. Click on one of the job groups buttons to upload pending jobs.
2. You can pull data of "other jobs" either from TOS, or upload your local .csv file.
3. Specify the earliest start and latest finish times on the bottom left.
4. Click on "RUN YCSM" button to execute the module.

**YARD CRANES STATUS**

ID	position	status
RTG_1	16 - 027 - 011	AVAILABLE
RTG_3	13 - 069 - 011	AVAILABLE
RTG_4	14 - 042 - 011	AVAILABLE
RTG_5	15 - 097 - 011	AVAILABLE
RTG_6	12 - 066 - 011	AVAILABLE
RS_12	13 - 089 - 011	AVAILABLE

HOUSEKEEPING JOBS

POSITIONING JOBS

OTHER JOBS (LOCAL FILE)

OTHER JOBS (TOS SERVER)

EARLIEST START	07/07/2021	17:37
LATEST FINISH	07/07/2021	18:39

**PENDING YARD CRANE SCHEDULING JOBS**

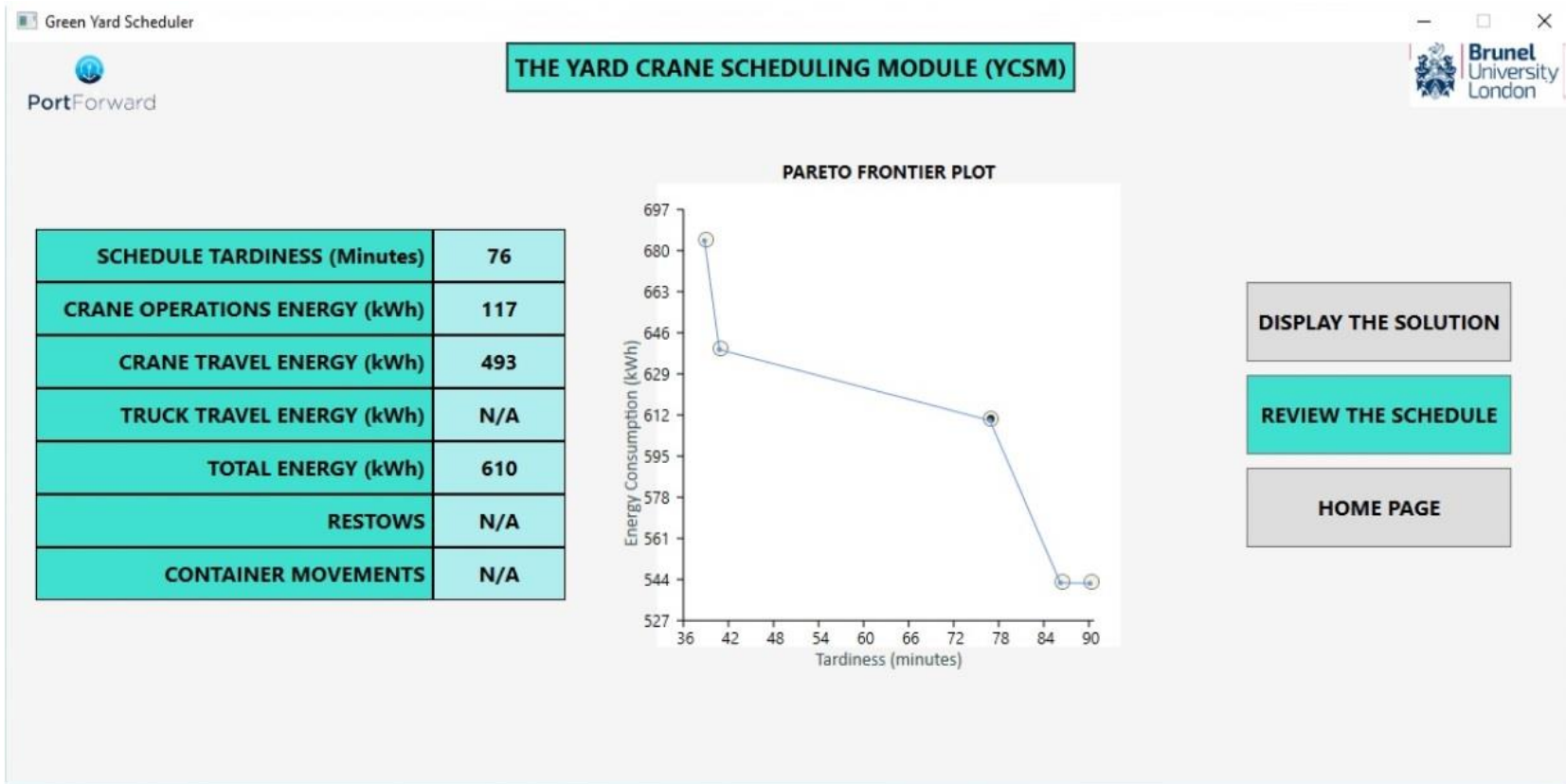
jobID	containerID	state	weight	operationType	initialPosition	finalPosition	registryDate	earliestStartTime	latestFinishTime	res
GI4_01		L	26100	LAND GATE IN	TERMINAL GATE	14 - 041 - 044	07/07/2021 17:22:31	07/07/2021 17:37:31	07/07/2021 18:39:50	NC
GO1_01		L	33000	LAND GATE OUT	14 - 075 - 021	TERMINAL GATE	07/07/2021 17:37:07	07/07/2021 17:52:07	07/07/2021 18:39:50	YES
GO5_01		V	2200	LAND GATE OUT	17 - 044 - 071	TERMINAL GATE	07/07/2021 17:38:56	07/07/2021 17:53:56	07/07/2021 18:39:50	NC
GO2_01		L	29092	LAND GATE OUT	14 - 075 - 032	TERMINAL GATE	07/07/2021 17:46:09	07/07/2021 18:01:09	07/07/2021 18:39:50	YES
GO3_01		L	9040	LAND GATE OUT	15 - 097 - 031	TERMINAL GATE	07/07/2021 17:49:56	07/07/2021 18:04:56	07/07/2021 18:39:50	NC
GI1_01		L	42420	LAND GATE IN	TERMINAL GATE	14 - 095 - 021	07/07/2021 17:51:30	07/07/2021 18:06:30	07/07/2021 18:39:50	YES
GI2_01		L	38820	LAND GATE IN	TERMINAL GATE	13 - 069 - 041	07/07/2021 17:52:44	07/07/2021 18:07:44	07/07/2021 18:39:50	YES
GO4_01		L	30784	LAND GATE OUT	16 - 081 - 061	TERMINAL GATE	07/07/2021 17:53:03	07/07/2021 18:08:03	07/07/2021 18:39:50	YES
GI3_01		L	45020	LAND GATE IN	TERMINAL GATE	13 - 069 - 042	07/07/2021 17:53:34	07/07/2021 18:08:34	07/07/2021 18:39:50	YES
GI8_01		L	44620	LAND GATE IN	TERMINAL GATE	13 - 069 - 013	07/07/2021 17:55:20	07/07/2021 18:10:20	07/07/2021 18:39:50	YES
GI5_01		L	42820	LAND GATE IN	TERMINAL GATE	14 - 073 - 032	07/07/2021 17:57:07	07/07/2021 18:12:07	07/07/2021 18:39:50	YES
GO7_01		V	3800	LAND GATE OUT	17 - 029 - 062	TERMINAL GATE	07/07/2021 18:01:16	07/07/2021 18:16:16	07/07/2021 18:39:50	NC
GO10_01		L	18622	LAND GATE OUT	15 - 065 - 012	TERMINAL GATE	07/07/2021 18:06:56	07/07/2021 18:21:56	07/07/2021 18:39:50	NC

RUN YCSM

HOME PAGE

GO TO HKM

GO TO ICPM



- Future work

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# Thank you for your attention!

## Questions, comments?

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### Contact Details



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